

Model WPT-E\_-S

User Manual





Copyright © 2022 Michigan Scientific Corporation

Details and specifications provided in this document are purely for informational purposes and are subject to alterations. No liability is accepted for errors or omissions.

Michigan Scientific Corporation 8500 Ance Road Charlevoix, MI 49720

Revision Date: June 2, 2022 12:00 p.m. asjohnson

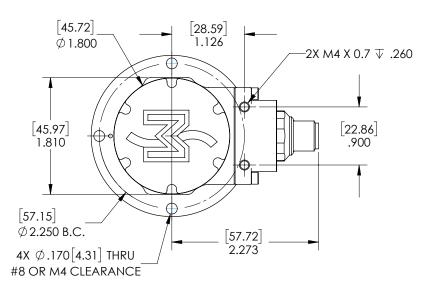
## **Contents**

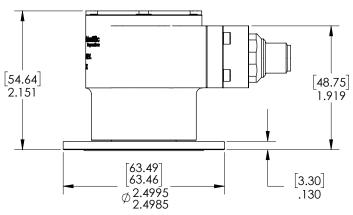
Introduction	1
Encoder Output	3
Installation	4
Technical Considerations	7
Mechanical Considerations	9
Cable Diagrams	10

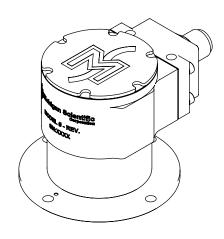
# High Resolution Wheel Pulse Transducer...

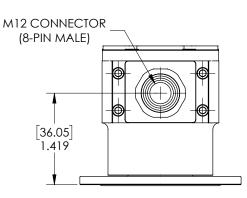
- · Contains precision electronics in a rugged housing
- Measures rotational velocity, angular position, and direction of rotation
- Used to determine wheel speed, acceleration, distance, and vehicle speed for GPS and map validation
- Mounts directly to production wheel
- Can be adapted to mount on many different vehicles

Specifications	
<b>Electrical Specifications</b>	
Input Voltage	+5 to +20 Vdc
Input Current	60 mA
Output Type	0-5 V TTL
Reverse Voltage Protection	20 V
Encoder Accuracy (Maximum Cumulative Error)	0.25°
<b>Mechanical Specifications</b>	
Size (W x D x H)	2.50 in x 2.15 in x 3.52 in (63.5 mm x 54.61 mm x 89.4 mm)
Weight (Sensor Only)	14.5 oz (410 g)
Temperature Range	Up to 2,000 ppr: -40° F to 212° F (-40° C to 100° C) 2,000 ppr and up: -13° F to 212° F (-25° C to 100°C)
Protection Rating	IP67, NEMA 6
Maximum Speed	2,000 r/min
Unit Torque	21 in·oz



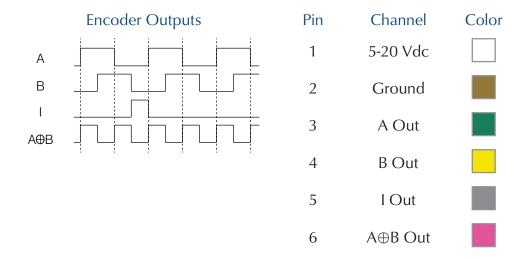




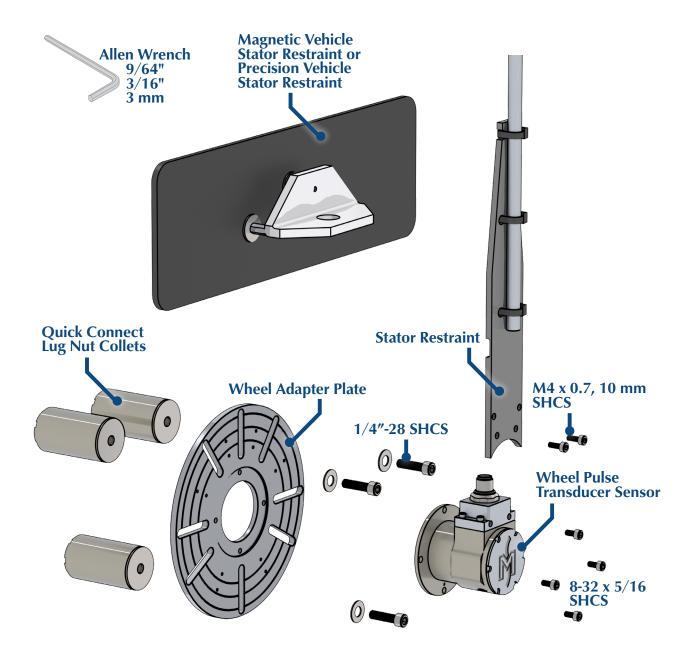


# **Encoder Output**

Optical encoder resolutions ranging from 32 to 5,000 pulses per revolution are offered. All encoder choices have four outputs. Outputs A and B are in quadrature, meaning they are 90° out of phase. Output I is an index pulse. Output  $A \oplus B$  is the exclusive OR of A and B, which doubles the basic resolution of the encoder. The outputs, 0 to 5 volt pulses, can drive TTL loads.



## Installation



## Mounting Plate Installation

- 1. Remove the 1/4"-28 socket head cap screw (SHCS) and small washer from the top of the Quick Connect Lug Nut Collets.
- 2. Place the Quick Connect Lug Nut Collets on the back side of the plate, keeping the large washer between the top of the collet and the plate.
- 3. Align the collets with the respective slots based on the total number of lugs.
- 4. Install the screw and washer through the plate and into the collet, but do not tighten the screw yet.

- 5. Attach the Quick Connect Lug Nut Collets to the vehicle lug nuts and tighten the screws until snug.
- 6. Using the concentric rings etched on the wheel plate as a guide, adjust the plate until it is centered on the wheel.
- 7. After the plate is centered, torque the screws to 75 in·lb (8.5 N·m).

# Magnetic Vehicle Stator Restraint (MVSR) or Precision Vehicle Stator Restraint (PVSR)

- 1. Assemble the MVSR/PVSR by threading the stand-offs into the plastic bracket.
- 2. Insert the 8-32 flat head screws through the back of the magnetic sheet into the threaded stand-offs.
- Attach the MVSR/PVSR to the body of the vehicle near the wheel so that the centerline of the magnetic sheet lines up with the center axis of the wheel.

**Optional:** Apply waterproof tape around the edges of the magnet on the vehicle to increase holding strength.

#### Wheel Pulse Transducer (WPT) Sensor

- 1. Pilot the rotor of the WPT sensor to the mounting plate.
- 2. Install four  $8-32 \times 5/16$  in SHCS to the rotor and mounting holes.
- 3. Torque the screws to 22 in·lb (2.5 N·m).

#### Stator Restraint

- 1. Insert the end of the stator restraint tube into the hole in the MVSR or PVSR.
- 2. Attach the plastic end of the stator restraint to the end of the encoder module using two M4 x 0.7, 10 mm length SHCS.
- 3. Torque screws to 25 in·lb (2.8 N·m).

#### **Notes**

It may be useful to use an angular measuring device to confirm that the magnetic sheet is properly aligned with the center axis of the wheel.

## Stator Cable

- 1. Attach the female connector end on the stator cable to the male connector on the WPT sensor.
- 2. Route the stator cable along the stator restraint tube, securing it with zip-ties.
- 3. Secure the cable to the body of the vehicle.
- 4. Wrap fusion tape around the connector and receptacle.

## Notes

Do not route the cable through the MVSR.

Leave enough slack in the cable to accommodate the full wheel travel. The cable must be routed so that the bend radius of the cable is greater than 2.25 in [57 mm] for the entire travel of the wheel.



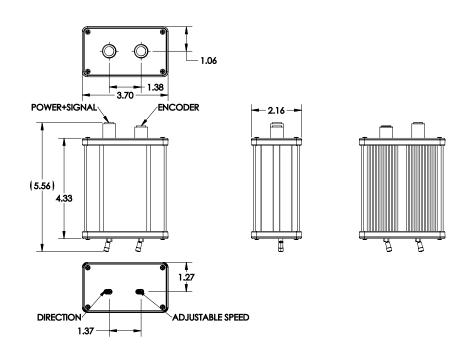
## **Technical Considerations**

## **Encoder Signal Conditioners**

Michigan Scientific Corporation manufacturers encoder signal conditioners which can be used to convert the digital pulses of the WPT sensor encoder to other signal formats. The EC-LV and EC-SC are small enclosures that can be added in-line with the stator cable and do not require any additional programming. The EC-LV converts digital pulses to linear voltages and the EC-SC converts digital pulses to digital sine and cosine waves.

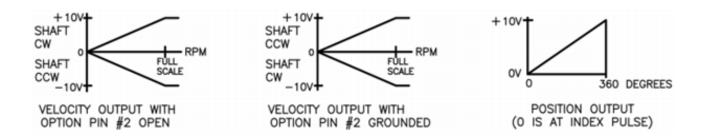
## **Specifications**

Electrical Specifications				
Input Voltage	+5 to +20 Vdc			
Maximum Input Current	270 mA			
Output Type (Angular Position)	0-10 Vdc			
Output Type (Angular Velocity)	± 10 Vdc			
Output Type (Sine-Cosine)	10 V peak-to-peak			
Reverse Voltage Protection	20 Vdc			
Mechanical Specifications				
Size (W x D x H)	5.6 in x 3.7 in x 2.2 in (142 mm x 94 mm x 56 mm)			
Weight	12.4 oz (351 g)			
Temperature Range	-40 °F to 212 °F (-40 °C to 100 °C)			
Protection Rating	IP40			



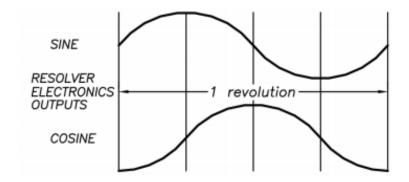
## **EC-LV Linear Voltage Conditioner**

The EC-LV conditioner converts 0-5 V digital pulses to linear voltages proportional to angular position and angular velocity. The external switches allow the user to select the speed range and direction of rotation. It outputs angular position and velocity signals in addition to the encoder signals.



### **EC-SC Sine-cosine Conditioner**

The EC-SC conditioner converts 0-5 V digital pulses to digital sine and cosine waves. The sine and cosine waves are 90° out of phase and one complete cycle is equivalent to one revolution of the vehicle wheel. The output voltages are 10 V peak-to-peak. The EC-SC has an external switch to select the direction of rotation.



## **Mechanical Considerations**

## **Quick Connect Lug Nut Collet Extensions**

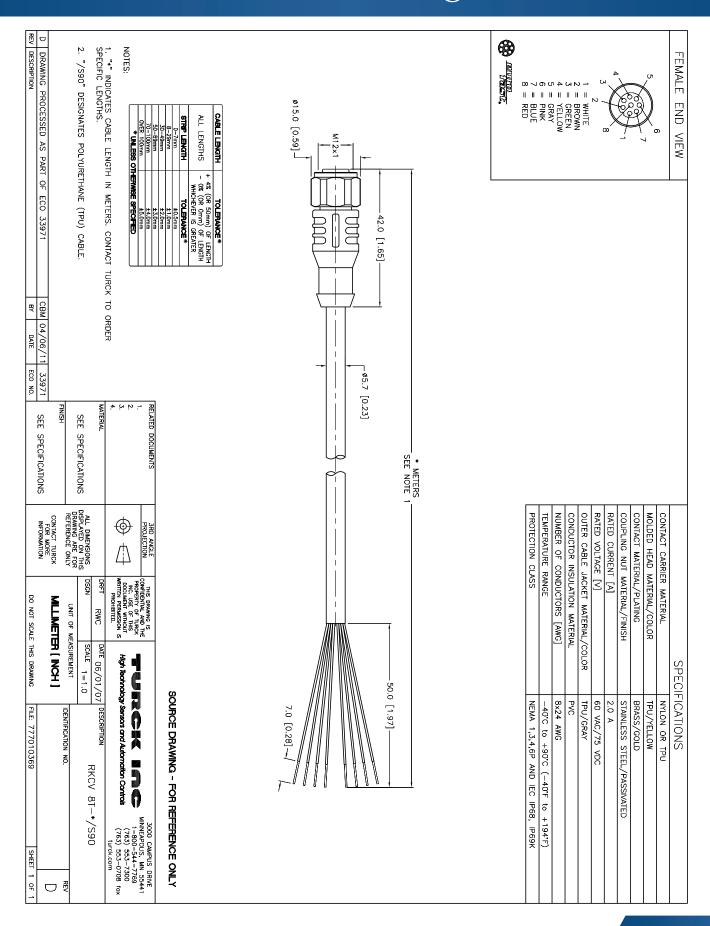
Michigan Scientific offers a wide variety of Quick Connect Lug Nut Collets that mount wheel adapter plates directly to a vehicle's original lug nuts. The table below shows the standard sizes available.

## **Quick Connect Collet Lug Nut Extension Specifications**

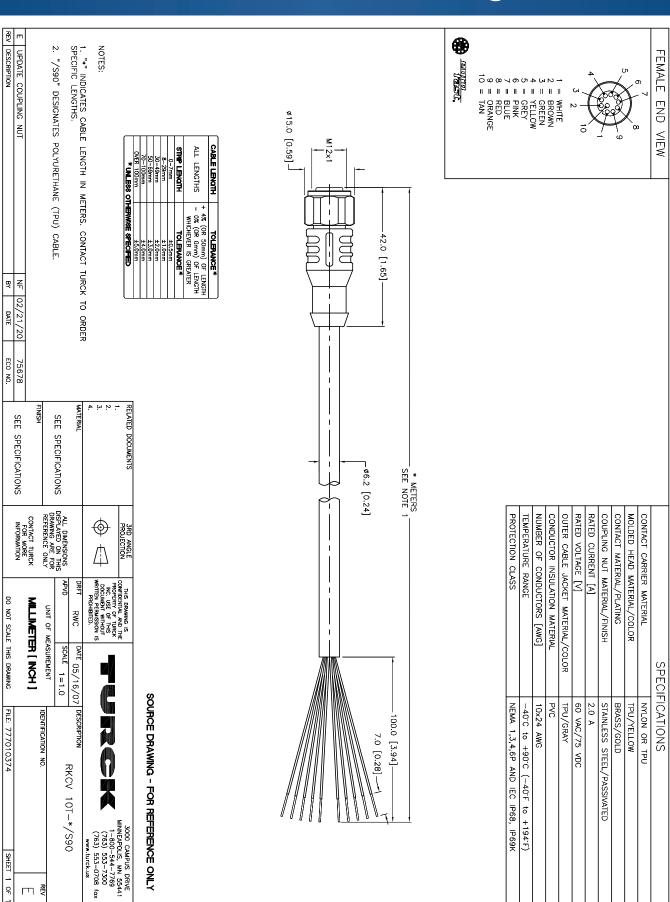
Model	Min. Lug Size (inch [mm])	Max. Lug Size (inch [mm])	Available Lengths (inch [mm])	Outside Diameter (inch [mm])
AAA	0.560	0.625	1.625, 2.500	0.945
	[14.2]	[15.9]	[41.3], [63.5]	[24.8]
AA	0.625	0.688	1.625, 2.500	0.945
	[15.9]	[17.5]	[41.3], [63.5]	[24.8]
Α	0.688	0.75	1.470, 1.625, 2.000, 3.000	1.100
	[1 <i>7</i> .5]	[19.1]	[37.3], [41.3], [50.8], [76.2]	[27.9]
AB	0.728	0.787	1.625	1.125
	[18.5]	[20.0]	[41.3]	[28.6]
ВВ	0.765	0.825	2.125, 3.000	1.270
	[19.4]	[21.0]	[54.0], [76.2]	[32.3]
В	0.813	0.875	2.125, 3.000	1.270
	[20.7]	[22.2]	[54.0], [76.2]	[32.3]
B-SS	0.813	0.875	2.125	1.220
	[20.7]	[22.2]	[54.0]	[31.0]
CCC	0.875	0.938	2.125, 3.000	1.302
	[22.2]	[23.8]	[54.0], [76.2]	[33.1]
CC	0.921	0.984	2.125, 3.000	1.470
	[23.4]	[25.0]	[54.0], [76.2]	[37.3]
С	1.000	1.063	2.125, 3.000	1.470
	[25.4]	[27.0]	[54.0], [76.2]	[37.3]
DD	1.125	1.188	3.000	1.630
	[28.6]	[30.2]	[76.2]	[47.4]
D	1.250	1.310	2.875	1.850
	[31.8]	[33.3]	[73.0]	[47.0]
D-HS	1.250	1.310	3.250	1.875
	[31.8]	[33.3]	[82.6]	[47.6]
DF	1.475	1.535	3.250	2.186
	[37.5]	[39.0]	[82.6]	[55.6]
F	1.563	1.625	3.250	2.186
	[38.3]	[41.3]	[82.6]	[55.6]



# WPT Cable Diagram



# EC-LV, EC-SC Cable Diagram



roved 02/21/2020, work order #208133 by D.C.